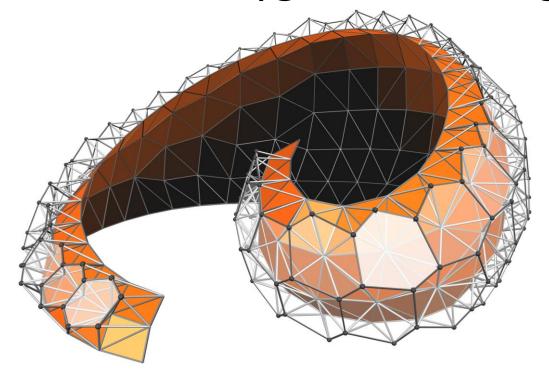
# Variational Tangent Plane Intersection for Planar Polygonal Meshing

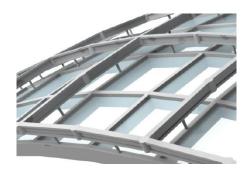


Henrik Zimmer, Marcel Campen, Ralf Herkrath, Leif Kobbelt



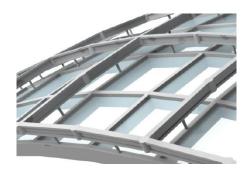


Multi-Layer Support Structures



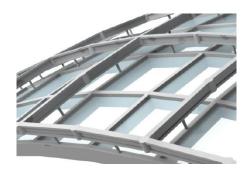


Multi-Layer Support Structures



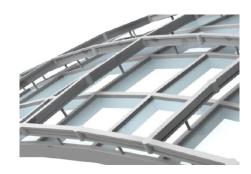


Multi-Layer Support Structures





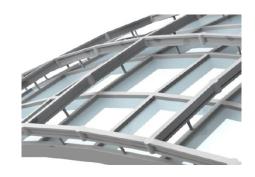
Multi-Layer Support Structures



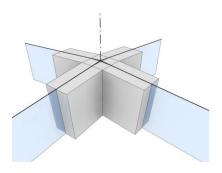
Supporting + Covering Layer



Multi-Layer Support Structures







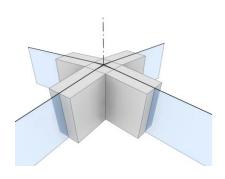
Node/edge simplicity



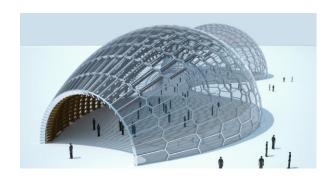
#### Multi-Layer Support Structures



Supporting + Covering Layer



Node/edge simplicity



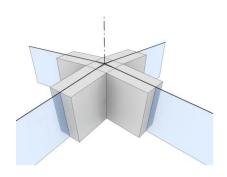
Planar panels



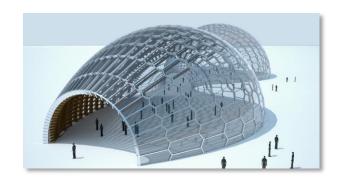
#### Multi-Layer Support Structures



Supporting + Covering Layer



Node/edge simplicity



Planar panels



Multi-Layer Support Structures







Multi-Layer Dual Structures



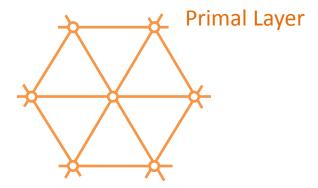
Multi-Layer Support Structures



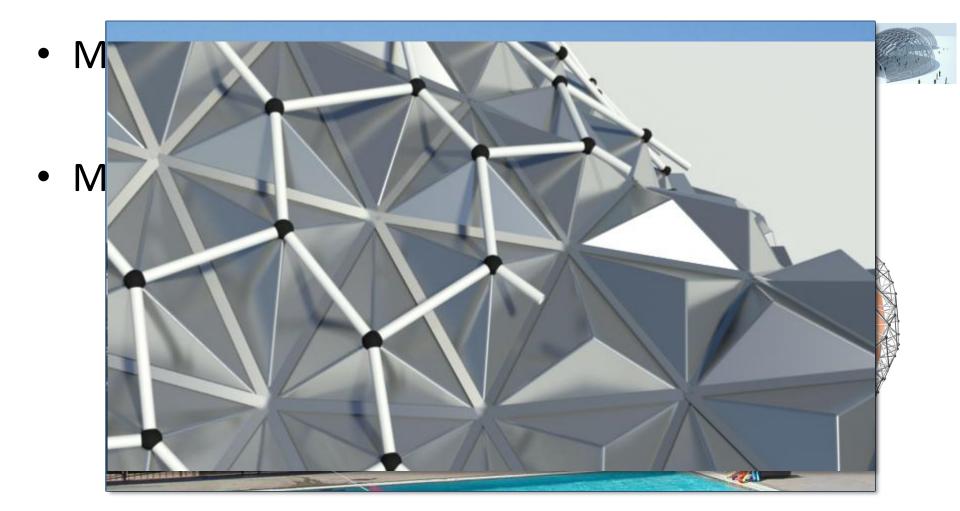




Multi-Layer Dual Structures









Multi-Layer Support Structures

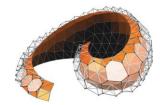






Multi-Layer Dual Structures







Multi-Layer Support Structures

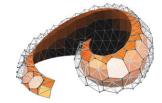




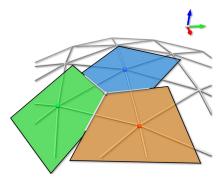


Multi-Layer Dual Structures





Tangent Plane Intersection (TPI)

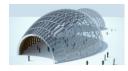




Multi-Layer Support Structures

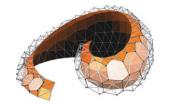




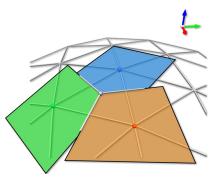


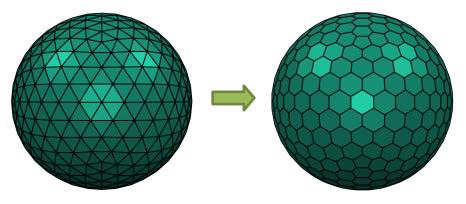
Multi-Layer Dual Structures





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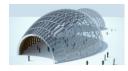




Multi-Layer Support Structures

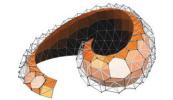






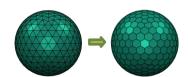
Multi-Layer Dual Structures





Tangent Plane Intersection (TPI)





Variational TPI



Multi-Layer Support Structures

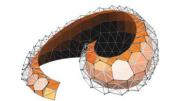






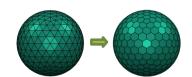
Multi-Layer Dual Structures



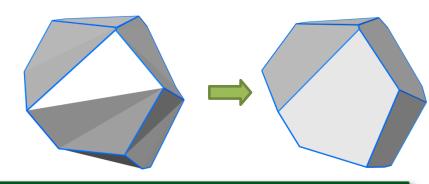


Tangent Plane Intersection (TPI)





- Variational TPI
  - Polygon Mesh Planarization

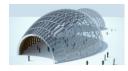




Multi-Layer Support Structures

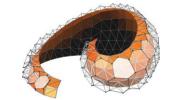






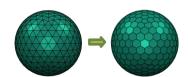
Multi-Layer Dual Structures



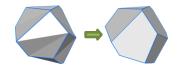


Tangent Plane Intersection (TPI)

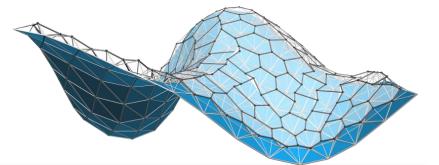




Variational TPI



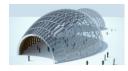
Dual Support Structures



Multi-Layer Support Structures

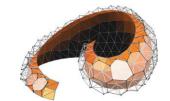






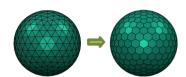
Multi-Layer Dual Structures



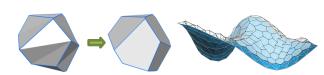


Tangent Plane Intersection (TPI)

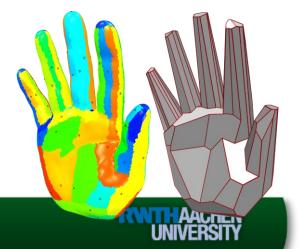








Variational Shape Approximation



Multi-Layer Support Structures

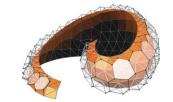






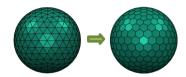
Multi-Layer Dual Structures



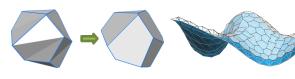


Tangent Plane Intersection (TPI)





Variational TPI







Multi-Layer Support Structures

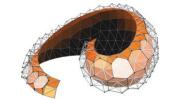






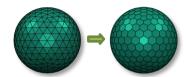
Multi-Layer Dual Structures



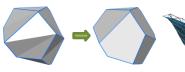


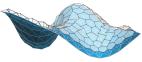
Tangent Plane Intersection (TPI)





Variational TPI





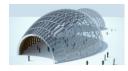




Multi-Layer Support Structures

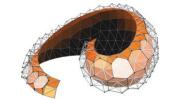






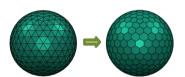
Multi-Layer Dual Structures



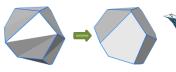


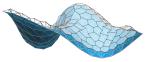
Tangent Plane Intersection (TPI)





Variational TPI





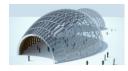




Multi-Layer Support Structures

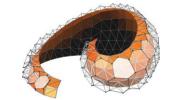






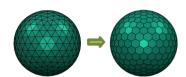
Multi-Layer Dual Structures



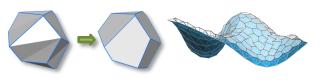


Tangent Plane Intersection (TPI)





Variational TPI







Multi-Layer Support Structures

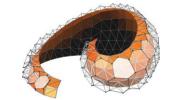






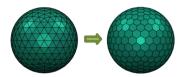
Multi-Layer Dual Structures



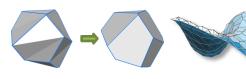


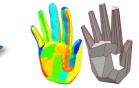
Tangent Plane Intersection (TPI)





Variational TPI



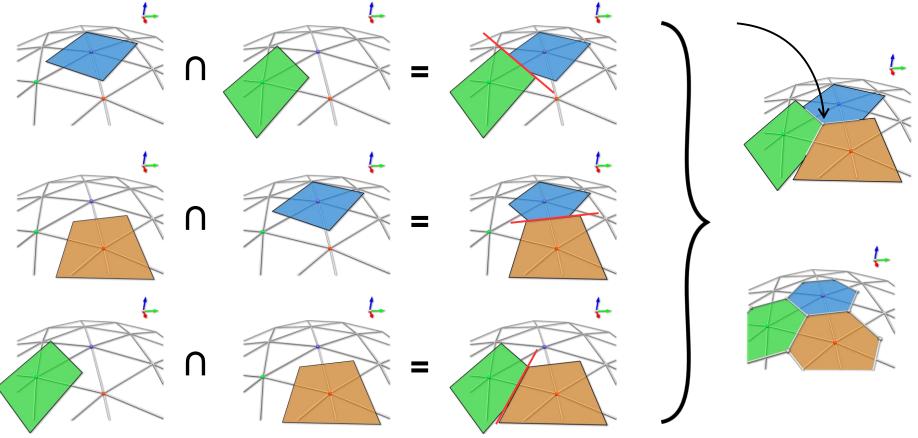




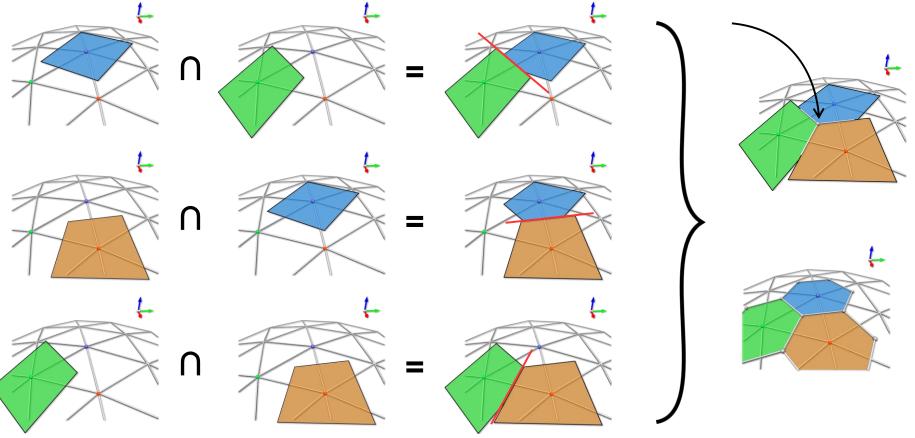
• 3 planes necessary for unique intersection point



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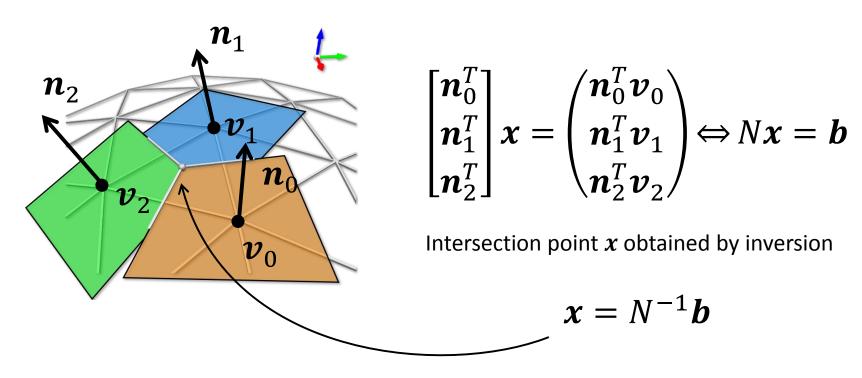
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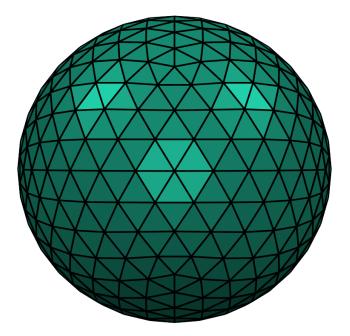


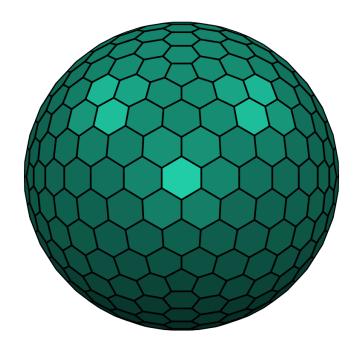
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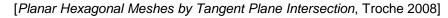




- 3 planes necessary for unique intersection point
  - Positive Curvature: OK

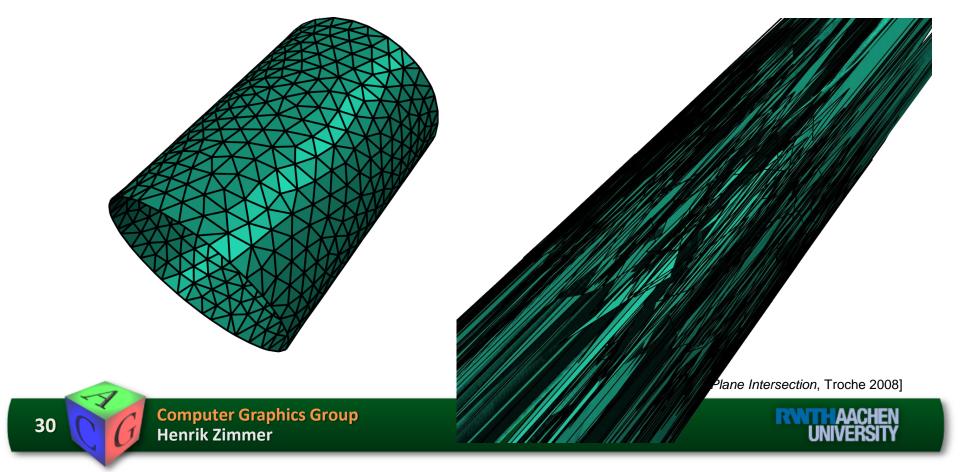




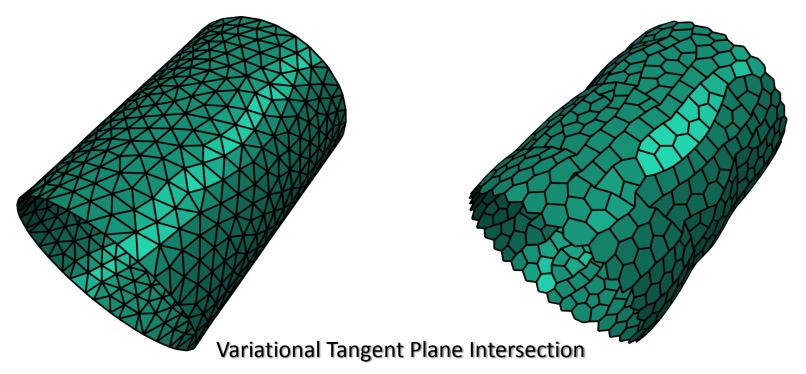


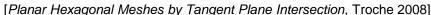


- 3 planes necessary for unique intersection point
  - Low Gaussian Curvature: UNSTABLE



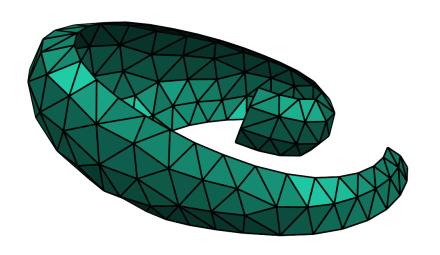
- 3 planes necessary for unique intersection point
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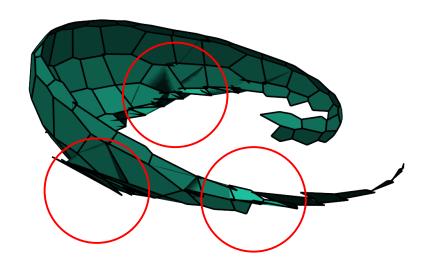


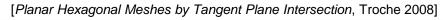




- 3 planes necessary for unique intersection point
  - Intersections are predetermined: No design DoFs

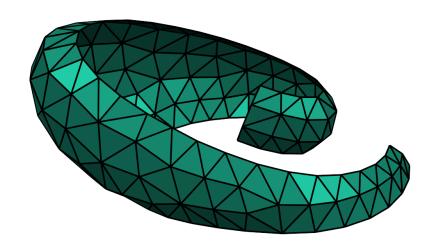


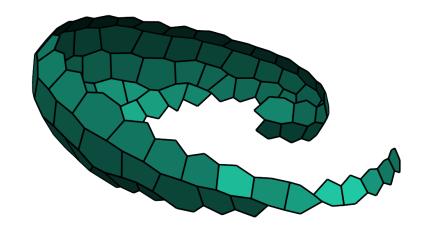






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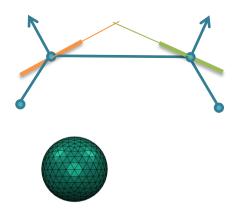
**Variational Tangent Plane Intersection** 

[Planar Hexagonal Meshes by Tangent Plane Intersection, Troche 2008]



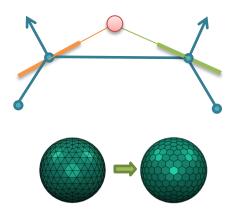


• Problem 1: Instability, co-planar tangent planes



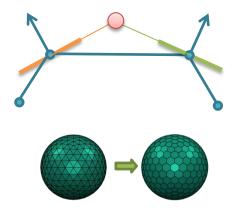


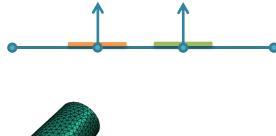
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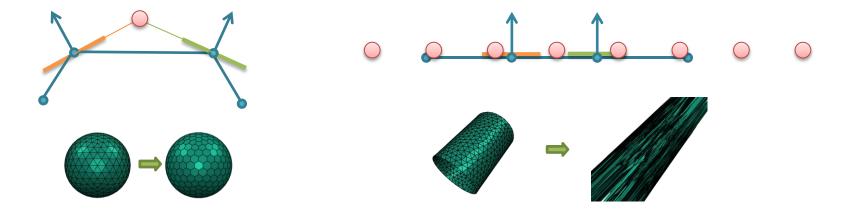






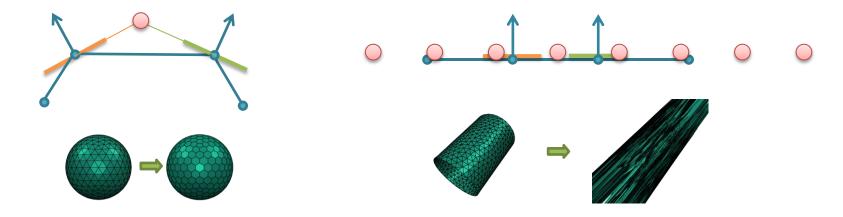


- Problem 1: Instability, co-planar tangent planes
  - Intersection point  $x = N^{-1}b$  is not well-defined



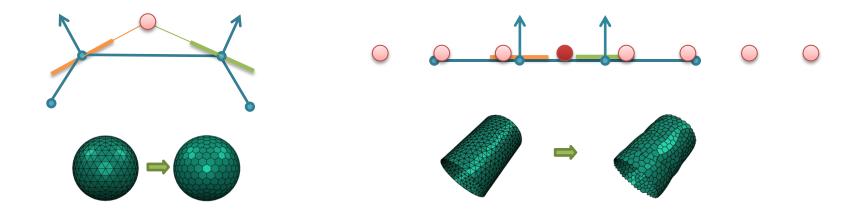


- Problem 1: Instability, co-planar tangent planes
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  - However, Nx = b still holds for all  $\circ$  points



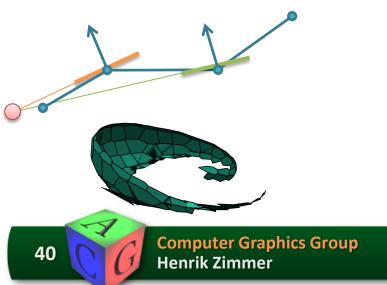


- Problem 1: Instability, co-planar tangent planes
  - Intersection point  $x = N^{-1}b$  is not well-defined
  - However, Nx = b still holds for all  $\circ$  points
    - → from all opoints we would like to choose our favorite •



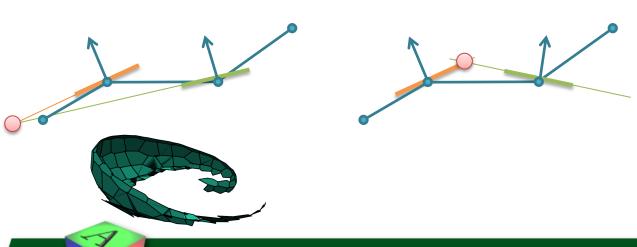


- Problem 2: bad (predetermined) intersections
  - Intersection is well-defined but position unwanted

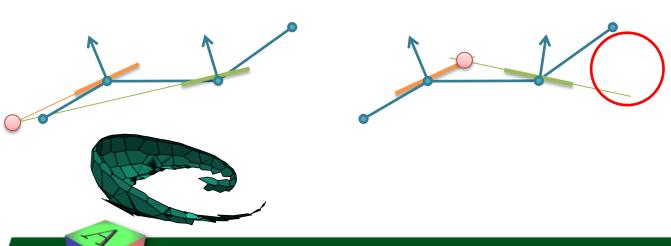




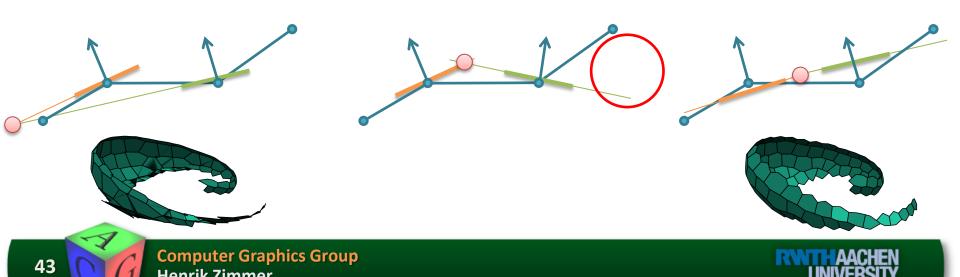
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  - Could obtain more degrees of freedom by:
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  - Could obtain more degrees of freedom by:
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    - offsetting tangent planes





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Formulate TPI as a constrained optimization:

minimize E s.t.  $C_{\text{int}}$ :  $N_f x_f = b_f \ \forall f \in F$ 

where  $x_f$  are the unknown intersection points



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where  $x_f$  are the unknown intersection points

 In non-degenerate configurations the solution is equivalent to the explicit TPI approach



$$C_{\text{int}}$$
:  $N_f x_f = b_f$ 

$$\forall f \in F$$



- Solution to Problem 1: instability
  - Specify energy with preferred intersection points  $oldsymbol{p}_f$

$$E := \sum_{f=0}^{\infty} ||\mathbf{x}_f - \mathbf{p}_f||^2$$
 s.t.  $C_{\text{int}}: N_f \mathbf{x}_f = \mathbf{b}_f$   $\forall f \in F$ 



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  - Introduce variable offsets  $h_v$

$$E \coloneqq \sum_{f \in F} \|\boldsymbol{x}_f - \boldsymbol{p}_f\|^2$$
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- Solution to Problem 1: instability
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- Solution to Problem 2: "bad" intersection points
  - Introduce variable offsets  $h_{oldsymbol{v}}$  and normals  $oldsymbol{n}_{oldsymbol{v}}$

$$E \coloneqq \sum_{f \in F} \|\boldsymbol{x}_f - \boldsymbol{p}_f\|^2 \quad \text{s.t.} \quad \begin{array}{c} C_{\text{int}} \colon N_f \boldsymbol{x}_f = \boldsymbol{b}_f - \boldsymbol{h}_f \quad \forall f \in F \\ C_{\text{norm}} \colon \|\boldsymbol{n}_v\|^2 = 1 \quad \forall v \in V \end{array}$$



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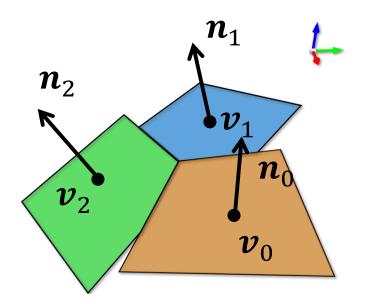
$$E := \sum_{f \in F} \|\boldsymbol{x}_f - \boldsymbol{p}_f\|^2 \quad \text{s.t.} \quad \begin{array}{c} C_{\text{int}} \colon N_f \boldsymbol{x}_f = \boldsymbol{b}_f - \boldsymbol{h}_f \quad \forall f \in F \\ C_{\text{norm}} \colon \|\boldsymbol{n}_v\|^2 = 1 \quad \forall v \in V \end{array}$$

So far VTPI is defined for triangle meshes ...





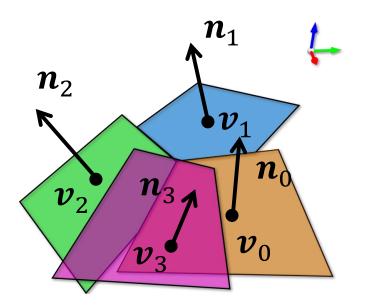
• 3 planes *necessary* for unique intersection point



$$\begin{bmatrix} \boldsymbol{n}_0^T \\ \boldsymbol{n}_1^T \\ \boldsymbol{n}_2^T \end{bmatrix} \boldsymbol{x} = \begin{pmatrix} \boldsymbol{n}_0^T \boldsymbol{v}_0 \\ \boldsymbol{n}_1^T \boldsymbol{v}_1 \\ \boldsymbol{n}_2^T \boldsymbol{v}_2 \end{pmatrix} \Leftrightarrow N \boldsymbol{x} = \boldsymbol{b}$$



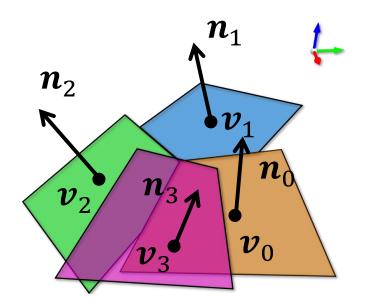
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• 3 planes *necessary* for unique intersection point

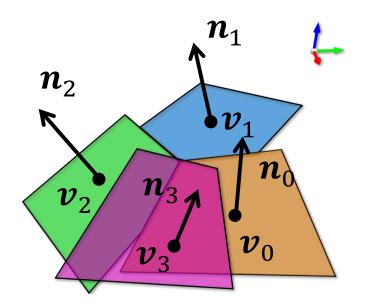


$$\begin{bmatrix} \boldsymbol{n}_0^T \\ \boldsymbol{n}_1^T \\ \boldsymbol{n}_2^T \\ \boldsymbol{n}_3^T \end{bmatrix} \boldsymbol{x} = \begin{pmatrix} \boldsymbol{n}_0^T \boldsymbol{v}_0 \\ \boldsymbol{n}_1^T \boldsymbol{v}_1 \\ \boldsymbol{n}_2^T \boldsymbol{v}_2 \\ \boldsymbol{n}_3^T \boldsymbol{v}_3 \end{pmatrix} \Leftrightarrow N\boldsymbol{x} = \boldsymbol{b}$$

No longer limited to triangle meshes



• 3 planes *necessary* for unique intersection point



$$\begin{bmatrix} \boldsymbol{n}_0^T \\ \boldsymbol{n}_1^T \\ \boldsymbol{n}_2^T \\ \boldsymbol{n}_3^T \\ \vdots \end{bmatrix} \boldsymbol{x} = \begin{pmatrix} \boldsymbol{n}_0^T \boldsymbol{v}_0 \\ \boldsymbol{n}_1^T \boldsymbol{v}_1 \\ \boldsymbol{n}_2^T \boldsymbol{v}_2 \\ \boldsymbol{n}_3^T \boldsymbol{v}_3 \\ \vdots \end{pmatrix} \Leftrightarrow N\boldsymbol{x} = \boldsymbol{b}$$

Works on general polygon meshes





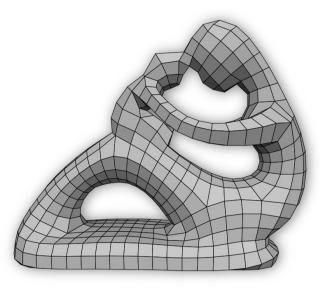
•  $M \mapsto \operatorname{planar} \operatorname{dual}(M)$ 



- $M \mapsto \text{planar dual}(M)$
- $dual(M) \mapsto planar M$



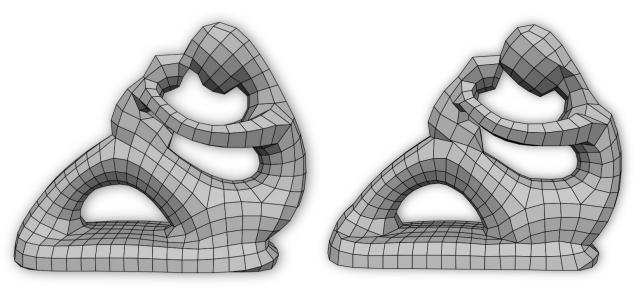
- $M \mapsto \text{planar dual}(M)$
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FERTILITY



- $M \mapsto \mathsf{planar} \, \mathsf{dual}(M)$
- $dual(M) \mapsto planar M$

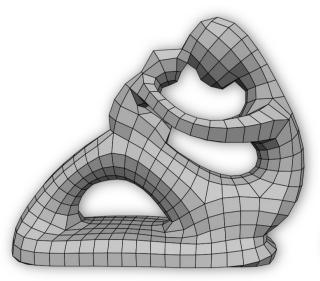


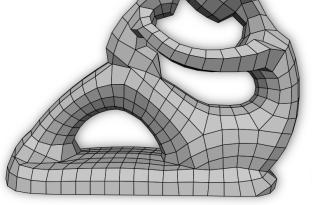
FERTILITY

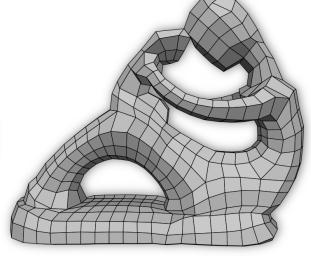




- $M \mapsto \mathsf{planar} \, \mathsf{dual}(M)$
- $dual(M) \mapsto planar M$







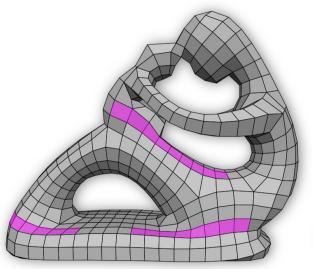
FERTILITY

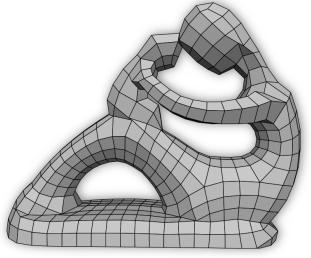
[Variational Tangent Plane Intersection]

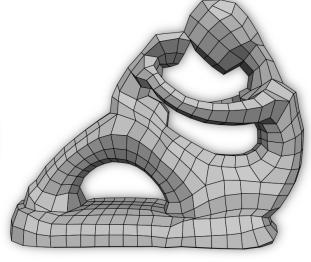




- $M \mapsto \mathsf{planar} \, \mathsf{dual}(M)$
- $dual(M) \mapsto planar M$
- Consider quad strips undergoing twists







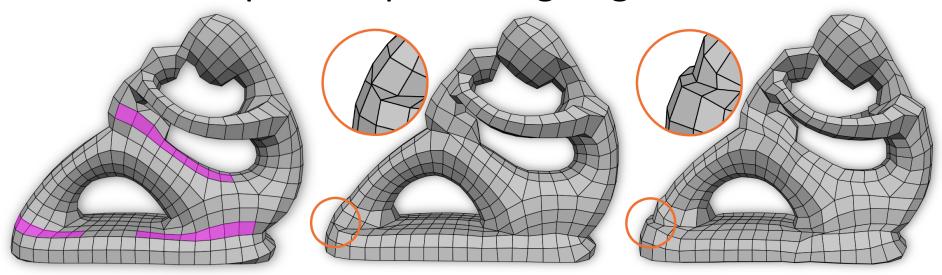
FERTILITY

[Variational Tangent Plane Intersection]





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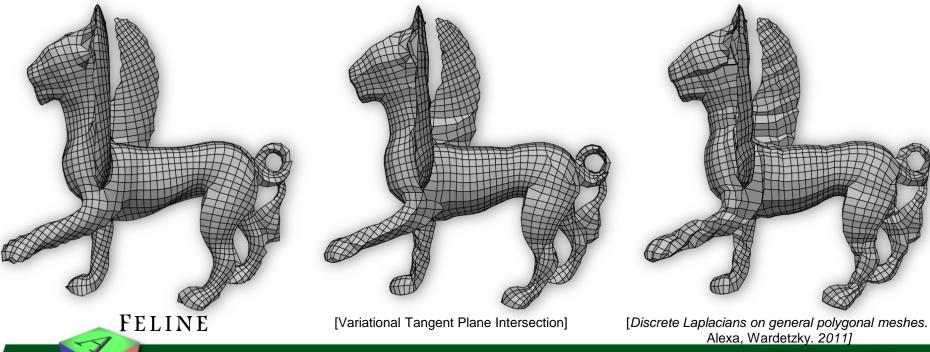
**FERTILITY** 

[Variational Tangent Plane Intersection]



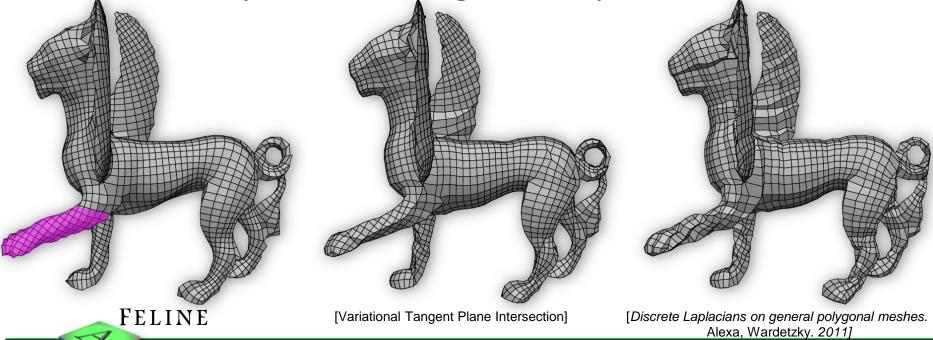


- $M \mapsto \mathsf{planar} \, \mathsf{dual}(M)$
- $dual(M) \mapsto planar M$



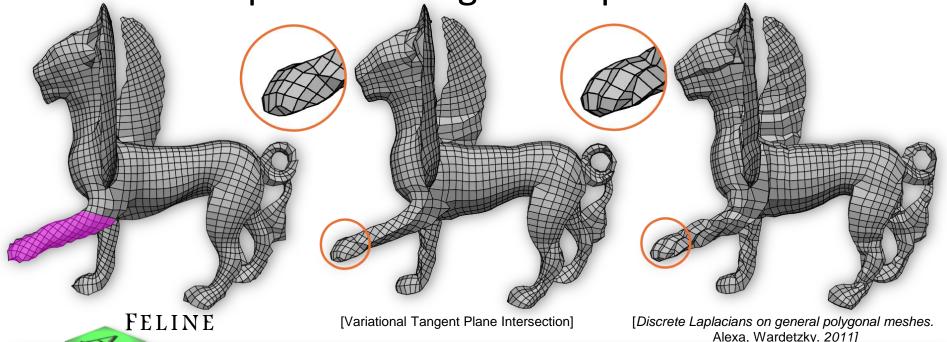
- $M \mapsto \mathsf{planar} \, \mathsf{dual}(M)$
- $dual(M) \mapsto planar M$

Consider quads not aligned to princ. curvatures



- $M \mapsto \mathsf{planar} \, \mathsf{dual}(M)$
- $dual(M) \mapsto planar M$

Consider quads not aligned to princ. curvatures



- Comparison to other planarization techniques
  - Optimization (perturbation)-based methods

[Hexagonal Meshes with Planar Faces. Wang, Liu, Yan, Chan, Ling, Sun. 2008]
[Geometric Modeling with Conical Meshes and Developable Surfaces. Liu, Pottmann, Wallner, Yang, Wang. 2006]

Planarizing flow

		Method		
		VTPI	Opt.	Flow
Property	Parameters	-	-	+
	Extensions	+	+	-
	Normals	+	-	-



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Planarizing flow

		Method		
		VTPI	Opt.	Flow
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## VTPI for Polygon Mesh Planarization

- Comparison to other planarization techniques
  - Optimization (perturbation)-based methods

[Hexagonal Meshes with Planar Faces. Wang, Liu, Yan, Chan, Ling, Sun. 2008] [Geometric Modeling with Conical Meshes and Developable Surfaces. Liu, Pottmann, Wallner, Yang, Wang. 2006]

Planarizing flow

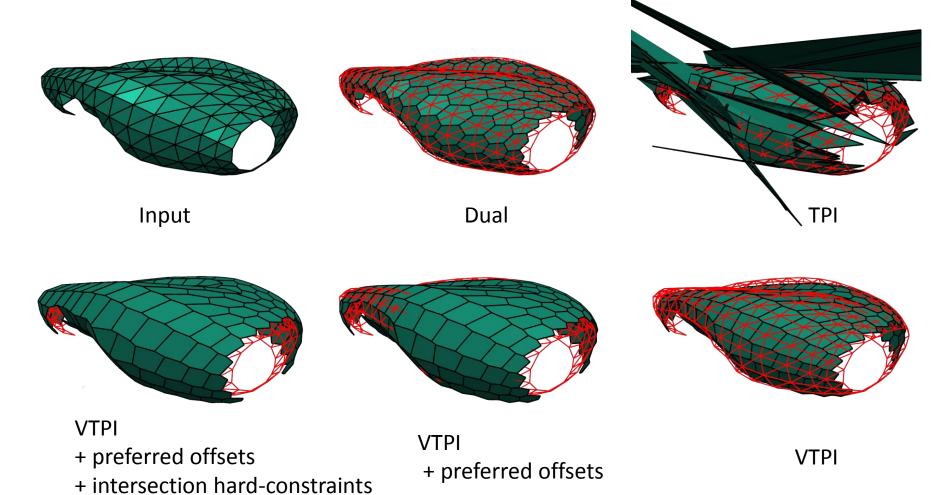
[Discrete Laplacians on general polygonal meshes. Alexa, Wardetzky. 2011]

		Method		
		VTPI	Opt.	Flow
Property	Parameters	-	-	+
	Extensions	+	+	-
	Normals	+	-	-

use normals → intersection-free dual structures



# VTPI for Multi-Layer Dual Structures







**Problem** 

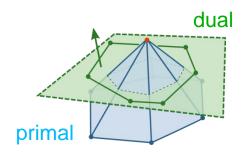
Solution (constraints)



**Problem** 

Solution (constraints)

Vertex Intersection

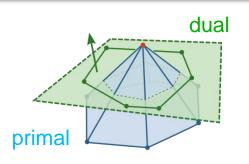


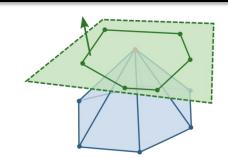


**Problem** 

Solution (constraints)

Vertex Intersection





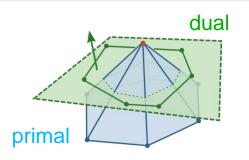
h > 0

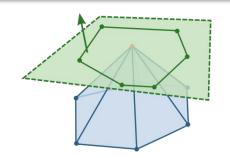


**Problem** 

Solution (constraints)

Vertex Intersection





h > 0

Face Intersection

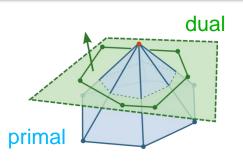


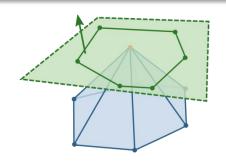


**Problem** 

Solution (constraints)

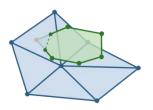
Vertex Intersection

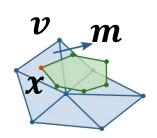




h > 0

Face Intersection



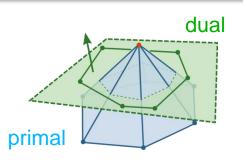


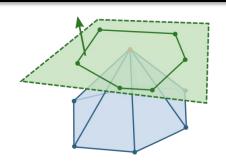
 $m^T(x-v) > 0$ 

**Problem** 

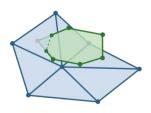
Solution (constraints)

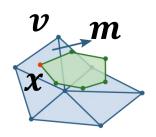
Vertex Intersection





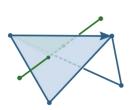
Face Intersection





$$m^T(x-v) > 0$$

Edge Intersection

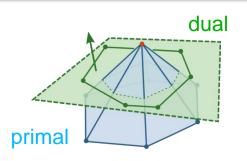


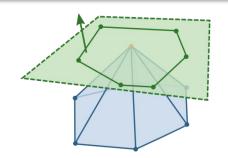


**Problem** 

Solution (constraints)

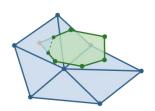
Vertex Intersection

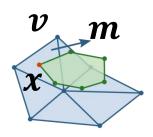






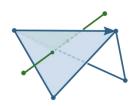
Face Intersection

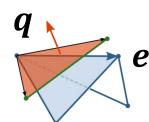




$$\boldsymbol{m}^T(\boldsymbol{x}-\boldsymbol{v})>0$$

Edge Intersection





$$q^T e < 0$$



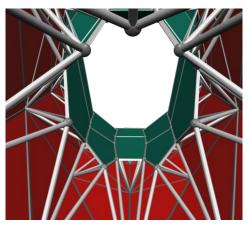
## Results of Multi-Layer Dual Structures

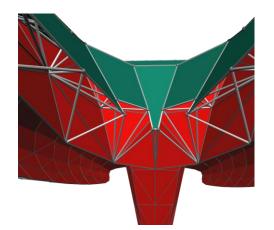


# Results of Multi-Layer Dual Structures



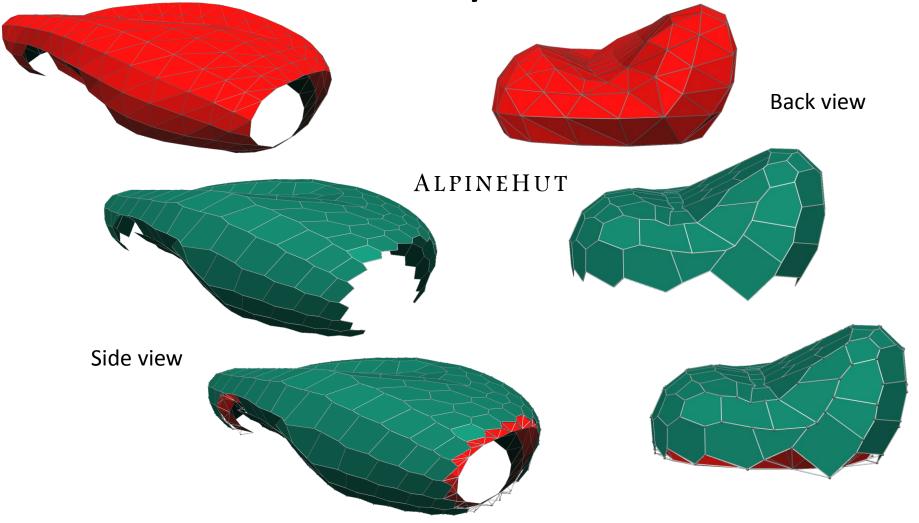








## Results of Multi-Layer Dual Structures





## Conclusion

What is VTPI?



### Conclusion

- What is VTPI?
  - A variational formulation of tangent plane intersection
    - Guided intersections of several planes
    - Useful for geometric problems (e.g. mesh planarization)
    - Solved by global optimization (freely available solvers)



## Conclusion

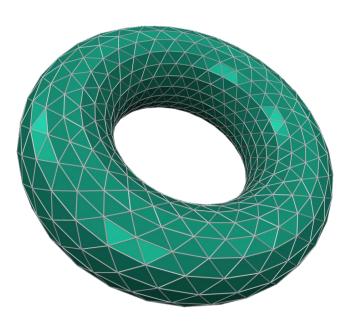
- What is VTPI?
  - A variational formulation of tangent plane intersection
    - Guided intersections of several planes
    - Useful for geometric problems (e.g. mesh planarization)
    - Solved by global optimization (freely available solvers)
- What is VTPI not?
  - A "fix" to topological issues involved in planar meshing
    - Degeneracies will occur where necessary, e.g. concave (or degenerate) hexagons in hyperbolic surface regions
    - Energies can sometimes be used to shift such effects ...



Output depends on input tessellation and energy



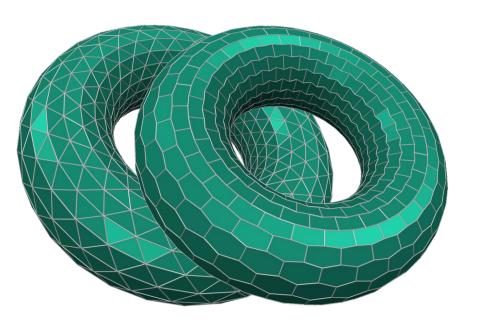
- Output depends on input tessellation and energy
  - Different tessellations, same topology

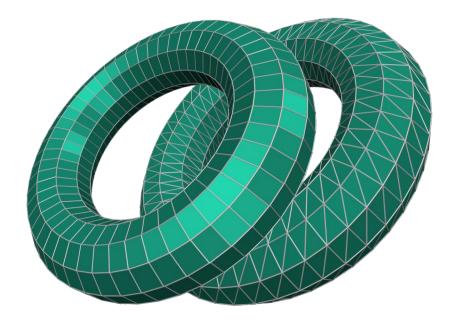






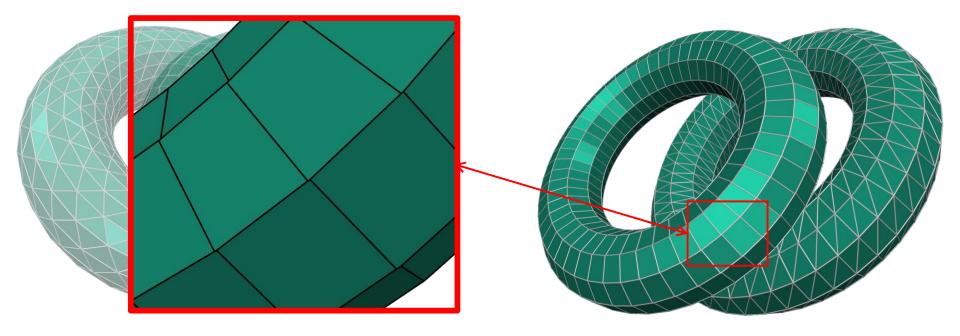
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  - Different tessellations, same topology, same functional







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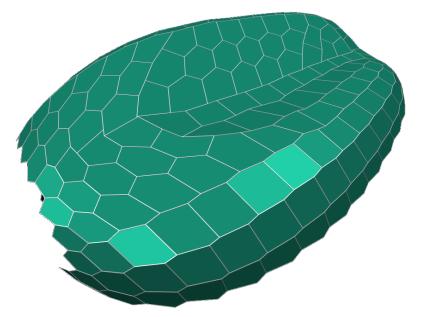




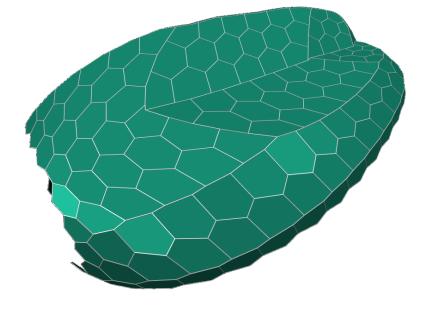
- Output depends on input tessellation and energy
  - energies can partly shift some effects on the mesh



- Output depends on input tessellation and energy
  - Same tessellation, same topology, different functional



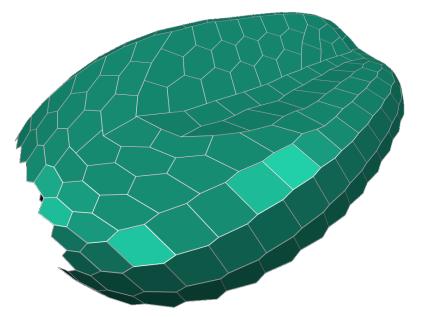
Normal Smoothness



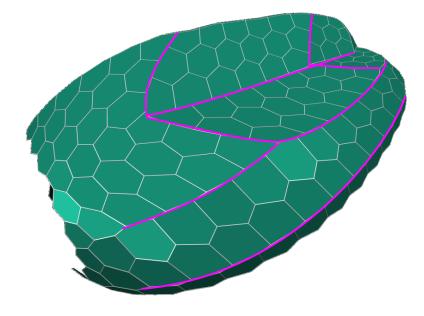
**Element Fairing** 



- Output depends on input tessellation and energy
  - Same tessellation, same topology, different functional



Normal Smoothness



**Element Fairing** 



## The End

Thank you for your attention!

